## DO NOT FORGET TO WRITE YOUR SID NO. ON YOUR EXAM.

ALL PROBLEMS HAVE EQUAL VALUE. There are 7 problems.

MA: Do any 5 problems.

Ph.D.: Do 5 problems and only 3 of them from 1, 2, 3, and 4.

[1] (a) Derive an expression for the truncation error of the standard second order difference approximation to  $\frac{d^2u}{dx^2}$ ,

$$\frac{d^2u}{dx^2} \simeq \frac{u_{n+1} - 2u_n + u_{n-1}}{h^2}$$

where  $u_n$  is the value of a function u at the nth point of a grid with mesh size h.

(b) Using the result in (a), derive the order of the local truncation error of the scheme

$$\frac{u_{n+1} - 2u_n + u_{n-1}}{h^2} = f_n + \frac{h^2}{12} \left( \frac{f_{n+1} - 2f_n + f_{n-1}}{h^2} \right)$$

when used to solve the differential equation

$$\frac{d^2u}{dx^2} = f \qquad u(a) = u(b) = 0$$

[2] Consider using Newton's method to find the root of the polynomial

$$p(x) = (x-1)^2 = x^2 - 2x + 1$$

- (a) Does the Newton iteration converge for all initial guesses? Justify your answer.
- (b) When it converges, what is the rate of convergence? Justify your answer.

[3] Let A be a symmetric positive definite matrix. At the end of the first step of the LU factorization of A without pivoting, we have

$$A^{(1)} = \begin{pmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ \hline 0 & & & & \\ \vdots & & & A' & \\ 0 & & & & \end{pmatrix}$$

- (a) Prove that A' is also symmetric and positive definite.
- (b) Using the result from (a), prove that the LU factorization of a symmetric positive definite matrix obtained without pivoting always exists.
- [4] Euler's method for solving  $\frac{dy}{dt} = f(y)$  is given by

$$y_{n+1} = y_n + dt \ f(y_n) \qquad n \ge 1$$

Consider two methods of using this scheme to advance from  $y_n$  to  $y_{n+1}$ ;  $y^{(1)}$  uses a step size of dt, while  $y^{(2)}$  uses two steps of size dt/2 (see Figure 1).

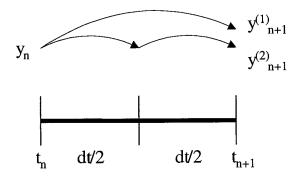


Figure 1.

- (a) Let  $y_{n+1}^{(*)} = \alpha y_{n+1}^{(1)} + \beta y_{n+1}^{(2)}$ , how should the values of  $\alpha$  and  $\beta$  be chosen so that  $y_{n+1}^{(*)}$  is a more accurate solution to the differential equation than either  $y_{n+1}^{(1)}$ , or  $y_{n+1}^{(2)}$ ? Justify your answer.
- (b) For your choice of  $\alpha$  and  $\beta$  what is the order of the local truncation error associated with the scheme that advances the solution using  $y_{n+1}^{(*)} = \alpha y_{n+1}^{(1)} + \beta y_{n+1}^{(2)}$ ? What is the order of the global error of the method?

[5] Consider the initial value problem

$$\begin{array}{rcl} u_t & = & v_x \\ v_t & = & 0 \end{array}$$

to be solved for  $0 \le x \le 1$ ,  $t \ge 0$ , with initial and boundary and conditions,

$$\begin{array}{rcl}
u(x,0) & = & \phi(x) & u(1,t) & = & u(0,t) \\
v(x,0) & = & \psi(x) & v(1,t) & = & v(0,t)
\end{array} \tag{4.1}$$

where  $\phi(x)$  and  $\psi(x)$  are smooth and periodic functions.

- (a) Can you write a stable, convergent finite difference scheme for this problem? Explain your answer and give an example of such a scheme if one exists.
- (b) Consider the related system

$$\begin{array}{rcl} u_t & = & v_x \\ v_t & = & \left(\frac{1}{100}\right) u_x \end{array}$$

with initial and boundary conditions (4.1). Can you write a stable, convergent finite difference scheme for this problem? Explain your answer and give an example of such a scheme if one exists.

[6] Consider the differential equation

$$u_t = u_{xx} + cu$$
  $c < 0$ 

with smooth initial data  $u_0(x) = u(x,0)$  and  $u_0(x)$ , u(x,t) periodic with period 1 in x.

- (a) Show that the solution decays in time for any initial data.
- (b) Construct a stable convergent finite difference scheme whose solutions are second order accurate in space and time and exhibit a similar decay in time. Justify your statements.
- [7](a)Derive a variational formulation of the convection-diffusion problem,

$$-\Delta u + a \cdot \nabla u + bu = f(x,y) \qquad 0 < x < 1, \qquad 0 < y < 1$$
 
$$u = c(x,y) \qquad x = 0, 1 \quad 0 \le y \le 1$$
 
$$\frac{\partial u}{\partial \vec{v}} = d(x,y) \qquad 0 < x < 1 \quad y = 0, 1$$

where a, b, c, d, and f are smooth functions.

(b) Let  $V_h$  be an appropriate finite element space (i.e. a space of functions with the requisite approximation properties). Show that the corresponding finite element approximation converges for b > 0. What happens when b = 0?