Qualifying Exam, Fall 2015 NUMERICAL ANALYSIS

DO NOT FORGET TO WRITE YOUR SID NO. ON YOUR EXAM.

There are 8 problems. Problems 1-4 are worth 5 points and problems 5-8 are worth 10 points. All problems will be graded and counted towards the final score.

You have to demonstrate a sufficient amount of work on both groups of problems [1-4] and [5-8] to obtain a passing score.

[1] (5 Pts.) Let A be an $n \times n$ a positive semi-definite symmetric matrix with a non-trivial null space, e.g. the dimension of $Ker(A) \neq 0$. Consider the problem

$$A\vec{x} = \vec{b} \tag{M}$$

- (a) State the condition that guarantees a solution to (M) will exist.
- (b) Give a derivation of the condition on the matrix A that insures the iterative method

$$\vec{x}_{k+1} = \vec{x}_k + (\vec{b} - A\vec{x}_k), \quad k = 0, 1, 2, \dots$$

will converge to a solution of (M), when a solution to (M) exists.

[2] (5 Pts.) Let $f(x), g(x) : \mathcal{R} \to \mathcal{R}$ be smooth functions and consider the problem of finding a solution to

$$f(x) + g(x) = b$$

(a) Assume one is given an approximate solution value x^{n-1} , derive the formula for the next approximation, x^n , that is obtained by using one step of Newton's method with starting iterate x^{n-1} applied to the problem

$$f(x) + g(x^{n-1}) = b$$

- (b) Assume that f is a linear function, under what conditions on f and g would you be able to prove that the iteration $x^{n-1} \to x^n$ defined by part (a) will converge? Explain your answer.
- [3] (5 Pts.) Recall that an $n \times n$ matrix A is strictly diagonally dominant if

$$|a_{ii}| > \sum_{j=1, j \neq i}^{n} |a_{ij}|$$

holds for each i = 1, 2, ..., n.

- (a) Show that the linear system Ax = b has a unique solution when A is strictly diagonally dominant.
- (b) Discuss the convergence of the Jacobi method for solving the linear system Ax = b when A is such a matrix. Justify your answer.

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[4] (5 Pts.) Let $f(x) = \ln(x+1)$, $x_0 = 0$, $x_1 = 0.6$ and $x_2 = 0.9$.

(a) Construct an interpolating polynomial of degree at most two to approximate f using the three points (you can use f(0.6) = 0.47 and f(0.9) = 0.6).

(b) Find an error bound for the approximation.

[5] (10 Pts.) Assume $f(y): \mathcal{R} \to \mathcal{R}$ is a smooth function and consider the initial value problem

$$\frac{\mathrm{d}y}{\mathrm{d}t} = f(y) \qquad y(0) = y_0 \tag{DE}$$

(a) Using expansions about t_n , derive the leading term of the local truncation error for the following method used to create approximate solutions to (DE),

$$y_n = y_{n-1} + \frac{3h}{2}f_{n-1} - \frac{h}{2}f_{n-2}$$

(b) Using (a) and the fact that the local truncation error estimate for the second order BDF method has the form

$$y_n = \frac{4}{3}y_{n-1} - \frac{1}{3}y_{n-2} + \frac{2h}{3}f_n - \frac{2}{9}h^3\frac{d^3y}{dt^3}(t_n) + O(h^4)$$

derive the leading term of the local truncation error for the method

$$y^* = y_{n-1} + \frac{3h}{2}f_{n-1} - \frac{h}{2}f_{n-2}$$

$$y_n = \frac{4}{3}y_{n-1} - \frac{1}{3}y_{n-2} + \frac{2h}{3}f(y^*)$$

(c) Derive the polynomial whose roots determine the region of absolute stability for the method in (b).

[6] (10 Pts.) Consider the initial value problem

$$u_t = -\left(\frac{u^3}{3}\right)_x + \epsilon u_{xx} \qquad \epsilon > 0$$

to be solved for $0 \le x \le 1$ with initial data $u(x,0) = \varphi(x)$, smooth and periodic boundary conditions

$$u(x+1,t) \equiv u(x,t).$$

- (a) Write a finite difference scheme that converges uniformly in ϵ as $\epsilon \downarrow 0$ for all t > 0.
- (b) Justify your answers.

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[7] (10 Pts.) Consider the initial boundary value problem

$$u_{tt} = u_{xx} - u$$

to be solved for

$$u(x,0) = \varphi(x)$$

$$u_t(x,0) = \psi(x)$$

 φ, ψ smooth.

(a) For which constant values a, b, c, d do the boundary conditions

$$au_x + bu_t = 0$$
 at $x = 0$

$$cu_x + du_t = 0 \quad \text{at } x = 1$$

lead to a well posed problem?

- (b) Write a convergent finite difference scheme for these well posed problems.
- (c) Justify your answers.
- [8] (10 Pts.) Consider the problem

$$-\Delta u + u = f(x, y) \qquad (x, y) \in \Omega,$$

$$u = 0 \qquad (x, y) \in \partial \Omega_1,$$

$$\frac{\partial u}{\partial \vec{n}} + u = x \qquad (x, y) \in \partial \Omega_2,$$

where

$$\Omega = \{(x,y): x^2 + y^2 < 1\},\$$

$$\partial \Omega_1 = \{(x,y): x^2 + y^2 = 1, x \le 0\},\$$

$$\partial \Omega_2 = \{(x,y): x^2 + y^2 = 1, x > 0\},\$$

and $f \in L^2(\Omega)$.

- (a) Determine an appropriate weak variational formulation.
- (b) Is the obtained bilinear form symmetric? If yes, give an equivalent minimization formulation.
- (c) Verify conditions on the corresponding linear and bilinear forms needed for existence and uniqueness of the solution to the weak variational formulation.
- (d) Assume that the boundary $\partial\Omega$ is approximated by a symmetric polygonal curve. Describe a finite element approximation of the problem using P_1 elements and a set of basis functions. Prove the necessary properties of the obtained linear system and discuss its structure. Give a rate of convergence.