

Optimization / Numerical Linear Algebra (ONLA)

INSTRUCTIONS FOR QUALIFYING EXAMS

Start each problem on a new sheet of paper. Write your university identification number at the top of each sheet of paper. **DO NOT WRITE YOUR NAME!**

Complete this sheet and staple to your answers. Read the directions of the exam carefully.

STUDENT ID NUMBER: _____

DATE: _____

EXAMINEES: DO NOT WRITE BELOW THIS LINE

1. _____

5. _____

2. _____

6. _____

3. _____

7. _____

4. _____

8. _____

Pass/fail recommend on this form.

Total score: _____

DO NOT FORGET TO WRITE YOUR SID NO. ON YOUR EXAM. PLEASE USE BLANK PAGES AT END FOR ADDITIONAL SPACE.

1. (10 points) Assume the Axiom of Floating Point Arithmetic (on \mathbb{R}) holds with machine precision $\varepsilon_{\text{machine}}$. Denote by \oplus and \ominus floating point addition and subtraction, respectively.
 - a) Prove that the same Axiom also holds for complex-valued subtraction, with $\varepsilon := C\varepsilon_{\text{machine}}$ for a constant C (explicitly calculate an appropriate C in your proof).
 - b) Define the floating point algorithm $\hat{f}(x, y) = \text{fl}(x) \oplus \text{fl}(y)$ for $x, y \in [0, \infty)$. Is this algorithm stable, backward stable, both, or neither? Prove your answers.
 - c) Define the floating point algorithm $\hat{f}(x) = \text{fl}(x) \oplus 1$ for $x \in [0, \infty)$. Is this algorithm stable, backward stable, both, or neither? Prove your answers (and don't forget to consider small $x \approx 0$).

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2. (10 points) Consider solving the least squares problem $\min_x \|Ax - b\|_2^2$ for full-rank $m \times n$ matrix ($m \geq n$).
- Assume A is a fixed diagonal matrix (with extra zero rows if $m > n$). Consider the problem that takes as input b and outputs the least squares minimizer x . Prove that the relative condition number (with respect to the Euclidean norm) of this problem is $\frac{\kappa(A)}{\eta \cos \theta}$, where $\eta = \frac{\|A\|_2 \|x\|_2}{\|Ax\|_2}$, $\theta = \cos^{-1} \frac{\|Ax\|_2}{\|b\|_2}$, and $\kappa(A) = \|A\|_2 \|A^\dagger\|_2$ is the condition number of A .
 - Now let A be an arbitrary full rank $m \times n$ matrix ($m \geq n$). Consider the same problem as in a). Prove that the problem has the same condition number as in part a) in this general case as well.

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3. (10 points) Let $A \in \mathbb{R}^{m \times n}$ with $m \geq n$ have full column rank, and let $\sigma_1 \geq \sigma_2 \geq \dots \geq \sigma_n > 0$ denote the singular values of A . Consider the least squares problem

$$\min_x \|Ax - b\|_2,$$

with exact (infinite precision) solution x^* .

- a) Write x^* in terms of the SVD of $A = U\Sigma V^*$.
 b) Denote again the condition number $\kappa(A) = \sigma_1/\sigma_n$. Show that the condition number of the normal equations matrix satisfies

$$\kappa(A^*A) = \kappa(A)^2.$$

Briefly explain the numerical implication of this result for solving the least squares problem by forming the normal equations and applying a Cholesky factorization.

- c) Assume that a computed solution \hat{x} is the exact solution of a perturbed problem

$$(A + \Delta A)\hat{x} = b + \delta b,$$

where the perturbations satisfy

$$\frac{\|\Delta A\|_2}{\|A\|_2} = O(\varepsilon), \quad \frac{\|\delta b\|_2}{\|b\|_2} = O(\varepsilon),$$

with ε denoting machine precision. Show that

$$\frac{\|\hat{x} - x^*\|_2}{\|x^*\|_2} = O(\kappa(A)\varepsilon).$$

Explain informally why solving the least squares problem via the normal equations typically leads to a forward error bound of order $O(\kappa(A)^2\varepsilon)$.

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4. (10 points) Let $A \in \mathbb{R}^{n \times n}$ be symmetric positive definite, and consider a matrix splitting $A = M - N$, where M is nonsingular. Define the associated iteration matrix $T = M^{-1}N$. Assume that $M + N$ is symmetric positive definite. Write the A -inner product, A -norm (for vector x) and A -norm (for matrix B) by

$$\langle x, y \rangle_A := x^T A y, \quad \|x\|_A := \sqrt{x^T A x}, \quad \|B\|_A := \sup_{x \neq 0} \frac{\|Bx\|_A}{\|x\|_A}.$$

- a) Prove that T is self-adjoint with respect to the A -inner product.
b) Show that the stationary iteration

$$x^{(k+1)} = T x^{(k)} + M^{-1}b$$

is a contraction in the A -norm if and only if $\rho(T) < 1$. (You may use the fact that it is a contraction if and only if $\|T\|_A < 1$).

- c) Explain whether or not this would hold for an arbitrary matrix norm.

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5. (10 points) Let $S \in \mathbb{R}^{n \times n}$ be symmetric and satisfy

$$\|S\|_2 \leq 0.5.$$

Define

$$A = I + S.$$

- (a) Show that A is symmetric positive definite
- (b) Consider the linear system

$$Ax = b$$

solved by the Conjugate Gradient method with initial guess $x^{(0)} = 0$. Give an upper bound on the number of CG iterations k required to guarantee

$$\frac{\|x - x^{(k)}\|_A}{\|x\|_A} \leq 10^{-15}.$$

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6. (10 points) Let an iterative method be defined by

$$x^{(k+1)} = Gx^{(k)} + c,$$

where $G \in \mathbb{R}^{n \times n}$ and $c \in \mathbb{R}^n$.

Assume x^* is a fixed point of the iteration, i.e.

$$x^* = Gx^* + c.$$

Define the error by

$$e^{(k)} = x^* - x^{(k)}.$$

(a) Show that the error satisfies

$$e^{(k+1)} = Ge^{(k)}.$$

(b) Show that if $\rho(G) < 1$, then the iteration converges to x^* for any initial guess.

(c) Show that if there exists a matrix norm such that $\|G\| < 1$, then the iteration converges to x^* .

(d) Give an example of a matrix G such that $\rho(G) < 1$ but $\|G\|_2 > 1$.

7. (10 points) Let $f : \mathbb{R}^n \rightarrow \mathbb{R}$ be a convex function, and suppose $x^* \in \mathbb{R}^n$ is a minimizer of f . Assume that every subgradient used by the algorithm satisfies

$$\|g_k\| \leq G, \quad g_k \in \partial f(x_k),$$

for some constant $G > 0$. Consider the subgradient iteration

$$x_{k+1} = x_k - \alpha_k g_k,$$

with step sizes

$$\alpha_k = \frac{\alpha}{\sqrt{k+1}}, \quad \alpha > 0.$$

- (a) Show that for every $k \geq 0$,

$$\|x_{k+1} - x^*\|^2 \leq \|x_k - x^*\|^2 - 2\alpha_k(f(x_k) - f(x^*)) + \alpha_k^2 G^2.$$

- (b) Deduce that for every $N \geq 0$,

$$\sum_{k=0}^N \alpha_k (f(x_k) - f(x^*)) \leq \frac{1}{2} \|x_0 - x^*\|^2 + \frac{G^2}{2} \sum_{k=0}^N \alpha_k^2.$$

- (c) Let

$$f_{\text{best}}^{(N)} := \min_{0 \leq k \leq N} f(x_k).$$

Show that

$$f_{\text{best}}^{(N)} - f(x^*) \leq \frac{\frac{1}{2} \|x_0 - x^*\|^2 + \frac{G^2}{2} \sum_{k=0}^N \alpha_k^2}{\sum_{k=0}^N \alpha_k}.$$

- (d) Using $\alpha_k = \alpha/\sqrt{k+1}$, show that

$$f_{\text{best}}^{(N)} - f(x^*) = O\left(\frac{\log N}{\sqrt{N}}\right).$$

8. (10 points) Let

$$F(x) = f(x) + g(x),$$

where $f : \mathbb{R}^n \rightarrow \mathbb{R}$ is convex and continuously differentiable with L -Lipschitz gradient, and $g : \mathbb{R}^n \rightarrow (-\infty, +\infty]$ is proper, closed, and convex. For $t > 0$, define the proximal operator

$$\text{prox}_{tg}(v) := \arg \min_{x \in \mathbb{R}^n} \left\{ g(x) + \frac{1}{2t} \|x - v\|^2 \right\}.$$

Consider the proximal gradient iteration

$$x_{k+1} = \text{prox}_{tg}(x_k - t\nabla f(x_k)), \quad 0 < t \leq \frac{1}{L}.$$

(a) Show that x_{k+1} minimizes the function

$$Q_k(x) := f(x_k) + \nabla f(x_k)^\top (x - x_k) + \frac{1}{2t} \|x - x_k\|^2 + g(x).$$

(b) Prove that for every k ,

$$F(x_{k+1}) \leq F(x_k) - \frac{1}{2} \left(\frac{1}{t} - L \right) \|x_{k+1} - x_k\|^2.$$

In particular, $F(x_k)$ is nonincreasing.

(c) Let x^* be a minimizer of F . Show that

$$F(x_{k+1}) - F(x^*) \leq \frac{1}{2t} \left(\|x_k - x^*\|^2 - \|x_{k+1} - x^*\|^2 \right).$$

(d) Deduce that

$$F(x_N) - F(x^*) \leq \frac{\|x_0 - x^*\|^2}{2tN} \quad \text{for all } N \geq 1.$$

9. (10 points) Consider the primal linear program

$$\begin{aligned} & \text{minimize } c^\top x \\ & \text{subject to } Ax \geq b, \\ & \quad \quad \quad x \geq 0, \end{aligned}$$

where $A \in \mathbb{R}^{m \times n}$, $b \in \mathbb{R}^m$, and $c \in \mathbb{R}^n$.

(a) Derive the dual problem.

(b) Prove *weak duality*: if x is primal feasible and y is dual feasible, then

$$b^\top y \leq c^\top x.$$

(c) Suppose x^* and y^* are primal and dual feasible, respectively. Show that if

$$c^\top x^* = b^\top y^*,$$

then both are optimal.

(d) Show that if x^* and y^* are optimal, then the complementary slackness conditions hold:

$$y_i^*(Ax^* - b)_i = 0 \quad \text{for } i = 1, \dots, m,$$

and

$$x_j^*(c - A^\top y^*)_j = 0 \quad \text{for } j = 1, \dots, n.$$